

LU decomposition

If we want to solve many different sets of equations

$$Ax = v$$

with the same matrix A but different v 's, it would be more efficient to do the full Gaussian elimination just once and

record the divisions, multiplications, and subtractions, so that later we can repeat it to any v .

This is what we call LU decomposition.

Using Python numbering, suppose we have the matrix

$$A = \begin{pmatrix} a_{00} & a_{01} & a_{02} & a_{03} \\ a_{10} & a_{11} & a_{12} & a_{13} \\ a_{20} & a_{21} & a_{22} & a_{23} \end{pmatrix}$$

$$A = \begin{pmatrix} a_{20} & a_{21} & a_{22} & a_{23} \\ a_{30} & a_{31} & a_{32} & a_{33} \end{pmatrix}$$

① The first step of the Gaussian elimination

is

-) to divide 1st row by a_{00} ,
so that the new 1st element $b_{00} = 1$
-) (2nd row) - a_{10} (new 1st row),
so that b_{10} becomes 0.
-) (3rd row) - a_{20} (new 1st row),
so that $b_{20} = 0$
-) (4th row) - a_{30} (new 1st row),
so that $b_{30} = 0$

This can be accomplished with a
single matrix multiplication

$$L_0 \cdot A = \begin{pmatrix} \textcircled{1} & b_{01} & b_{02} & b_{03} \\ \textcircled{0} & b_{11} & b_{12} & b_{13} \\ \textcircled{0} & b_{21} & b_{22} & b_{23} \\ \textcircled{0} & b_{31} & b_{32} & b_{33} \end{pmatrix}$$

$\underbrace{\hspace{15em}}_B$

where

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

where

$$L_0 = \frac{1}{a_{00}} \begin{pmatrix} 1 & 0 & 0 & 0 \\ -a_{10} & a_{00} & 0 & 0 \\ -a_{20} & 0 & a_{00} & 0 \\ -a_{30} & 0 & 0 & a_{00} \end{pmatrix}$$

⚠️ CHECK that this is true!

Note: L_0 is a lower triangular matrix

② The second step of the Gaussian elimination

.) divide 2nd row by b_{11} so $c_{11} = 1$

.) (3rd row) - b_{21} (new 2nd row) so $c_{21} = 0$

.) (4th row) - b_{31} (new 2nd row) so $c_{31} = 0$

$$L_1 \cdot B = \underbrace{\begin{pmatrix} 1 & b_{01} & b_{02} & b_{03} \\ 0 & 1 & c_{12} & c_{13} \\ 0 & 0 & c_{22} & c_{23} \\ 0 & 0 & c_{32} & c_{33} \end{pmatrix}}_C$$

where

$$L_1 = \frac{1}{b_{11}} \begin{pmatrix} b_{11} & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -b_{21} & b_{11} & 0 \\ 0 & -b_{31} & 0 & b_{11} \end{pmatrix}$$

(3) Third step

$$L_2 = \frac{1}{c_{22}} \begin{pmatrix} c_{22} & 0 & 0 & 0 \\ 0 & c_{22} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -c_{32} & c_{22} \end{pmatrix}$$

(4) Fourth step

$$L_3 = \frac{1}{d_{33}} \begin{pmatrix} d_{33} & 0 & 0 & 0 \\ 0 & d_{33} & 0 & 0 \\ 0 & 0 & d_{33} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Therefore, the complete Gaussian elimination

on A is equivalent to

$$\underbrace{L_3 \cdot L_2 \cdot L_1 \cdot L_0 \cdot A} = \underbrace{L_3 \cdot L_2 \cdot L_1 \cdot L_0 \cdot v}$$

this is an

UPPER-TRIANGULAR

matrix (which is the goal of the Gauss elimination)

this is a

new vector

The equation above can be solved with

BACKSUBSTITUTION

exactly as we did before.

The advantage now is that we have

$L_3 \ L_2 \ L_1 \ L_0 \ A$ stored

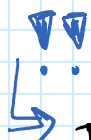
and

$L_3 \ L_2 \ L_1 \ L_0$ stored

and can solve the system of equations

for any v avoiding having to

compute $L_3 \cdot L_2 \cdot L_1 \cdot L_0 \cdot A$ again



In practice, however, the calculation is a

↳ In practice, however, the calculation is a little different.

We define

$$L = L_0^{-1} \cdot L_1^{-1} \cdot L_2^{-1} \cdot L_3^{-1} \quad \text{and} \quad U = L_3 L_2 L_1 L_0 A$$

\uparrow \uparrow
 for lower triangular matrix for upper triangular matrix

$L \cdot U = A$

↔
LU decomposition of matrix A

We can indeed verify that

$$L_0^{-1} = \begin{pmatrix} a_{00} & 0 & 0 & 0 \\ a_{10} & 1 & 0 & 0 \\ a_{20} & 0 & 1 & 0 \\ a_{30} & 0 & 0 & 1 \end{pmatrix}$$

$$L_1^{-1} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & b_{11} & 0 & 0 \\ 0 & b_{21} & 1 & 0 \\ 0 & b_{31} & 0 & 1 \end{pmatrix}$$

$$L_2^{-1} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & c_{22} & 0 \end{pmatrix}$$

$$L_3^{-1} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 & c_{22} & 0 \\ 0 & 0 & c_{32} & 1 \end{pmatrix} \quad \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & d_{33} \end{pmatrix}$$

$$L_0^{-1} L_1^{-1} L_2^{-1} L_3^{-1} = \begin{pmatrix} a_{00} & 0 & 0 & 0 \\ a_{10} & b_{11} & 0 & 0 \\ a_{20} & b_{21} & c_{22} & 0 \\ a_{30} & b_{31} & c_{32} & d_{33} \end{pmatrix}$$

Our set of equations can be written as

$$\underbrace{A} x = v$$

$$L U x = v$$

Taken as example a 3x3 case

$$\underbrace{\begin{pmatrix} l_{00} & 0 & 0 \\ l_{10} & l_{11} & 0 \\ l_{20} & l_{21} & l_{22} \end{pmatrix}}_L \cdot \underbrace{\begin{pmatrix} u_{00} & u_{01} & u_{02} \\ 0 & u_{11} & u_{12} \\ 0 & 0 & u_{22} \end{pmatrix}}_U \cdot \underbrace{\begin{pmatrix} x_0 \\ x_1 \\ x_2 \end{pmatrix}}_x = \underbrace{\begin{pmatrix} v_0 \\ v_1 \\ v_2 \end{pmatrix}}_v$$

we define
the vector y
as $U \cdot x = y$

$$\begin{pmatrix} y_0 \\ y_1 \\ y_2 \end{pmatrix}$$

which can be obtained by

BACK SUBSTITUTION

in $L \cdot y = v$ ↙

After obtaining y , we turn to

$U \cdot x = y$ to obtain x
also by

BACK SUBSTITUTION